

**AMENDMENTS TO THE CLAIMS**

1. (Currently amended) A device for generating a composite movement comprising:  
          , ~~in~~ a first movement section (~~L1~~) having a linear movement running in a longitudinal direction; (~~4~~) and, ~~in~~            a subsequent second movement section (~~L2~~), having a predetermined transverse movement (~~40~~) including a component perpendicular to the longitudinal direction (~~4~~);  
           - wherein said device comprising a linear member (~~2~~) movably guided in the longitudinal direction (~~4~~) and a transverse member (~~6~~) movably guided on the linear member (~~2~~) along a compensatory movement path (~~12~~), said compensatory movement path (~~12~~) including directional components in said longitudinal direction (~~4~~) and perpendicular thereto, and said transverse member (~~6~~) being mechanically forcibly guided within said second movement section (~~L2~~) of said linear member (~~2~~) in order to execute a relative displacement in said longitudinal direction (~~4~~) between said transverse member (~~6~~) and said linear member (~~2~~) such that, as a consequence of a kinematic superposition of the linear movement and a forcibly guided movement along said compensatory movement path (~~12~~), the predetermined transverse movement of said transverse member (~~6~~) results.
2. (Currently amended) The device as claimed in claim 1, ~~characterised in that~~ wherein the transverse movement is straight and runs at a predetermined angle  $\beta$  to the longitudinal direction (~~4~~).
3. (Currently amended) The device as claimed in either of claims 1 or 2, ~~characterised in that~~ wherein the compensatory movement path (~~12~~) runs in a straight line.

4. (Currently amended) The device as claimed in ~~any of the preceding claims 1~~, ~~characterised in that~~wherein the transverse movement runs perpendicular to the longitudinal direction-(4).
5. (Currently amended) The device as claimed in ~~any of the preceding claim s1~~, ~~characterised in that~~wherein the compensatory movement path (+2)-runs in a straight line at 45° to the longitudinal direction-(4).
6. (Currently amended) The device as claimed in claim 5, ~~characterised in that~~wherein the transverse member (6)-is forcibly guided in such a way that, within the second movement section (L2)-of the linear member (2)-~~it~~the transverse member remains absolutely still in the longitudinal direction-(4), so that, relative to the linear member-(2), it is displaced in the longitudinal direction-(4), corresponding to the linear movement thereof, but in the opposite direction.
7. (Currently amended) The device as claimed in ~~any of the preceding claim s1~~, ~~characterised in that~~wherein the transverse member (6)-is forcibly guided by means of a slide rod-(18).
8. (Currently amended) The device as claimed in claims 6-and 7, ~~characterised in that~~wherein the slide rod (+18)-is, at a first end, pivotably connected to the transverse member (6)-and, at a second end, guided by means of a stationary guide path-(26), having one part-(28) running in the longitudinal direction-(4), corresponding to the first movement section-(L1), and one part (32)-running perpendicular to the longitudinal direction-(4), corresponding to the second movement section-(L2).
9. (Currently amended) The device as claimed in claim 8, ~~characterised in that~~wherein a curved transition portion (30)-is provided between the first part-(28), running in the longitudinal

direction, and the second part ~~(32)~~, running perpendicular to the longitudinal direction.

10. (Currently amended) The device as claimed in ~~either of claims 8 or 9~~, characterised in that wherein the second end of the slide rod ~~(18)~~ is pivotably connected to a free end ~~(16a)~~ of a pivoting lever ~~(16)~~ which is mounted on the linear member ~~(2)~~ and is connected in a torsionally resistant manner to a control lever ~~(22)~~, the free end of which is guided in the guide path ~~(26)~~.
11. (Currently amended) The device as claimed in ~~any of the preceding claims 1~~, characterised in that wherein a holding and/or gripping means ~~(36)~~ is arranged on the transverse member ~~(6)~~ for holding, picking up and/or putting down an article.